

MERI College of Engineering and Technology (MERI - CET)

Lesson Plan

| Name of the Faculty | : | Mr. Pardeep | | | |
|--|---|--|--|--|--|
| Discipline | : | Mechanical Engineering | | | |
| Semester | : | 3 rd | | | |
| Subject | : | Engineering Mechanics (ESC-ME- 209G) | | | |
| Lesson Plan Duration | : | 15 Weeks (from Aug. 2020 to Nov. 2020) | | | |
| ** Work Load (Lecture) per week (in hours): Lectures-02, Practicals-00 | | | | | |

| Week | Theory | | Practical | |
|-----------------|-----------------|-----------------------------------|-----------|--------------|
| | Lecture | Торіс | Practical | Торіс |
| | Day | (including assignment/test) | day | _ |
| 1 st | 1 st | Introduction: Force system, | | No Practical |
| | | dimensions and units in | | |
| | | mechanics, laws of mechanics, | | |
| | | vector | | |
| | | algebra. | | |
| | 2^{nd} | Addition and subtraction of | | |
| | | forces, cross and dot products of | | |
| | | vectors, moment of a | | |
| | | force about a point and axis, | | |
| | | couple and couple moment, | | |
| | | transfer of a force to a parallel | | |
| and | and | position. | | |
| 2110 | 310 | Resultant of a force system using | | |
| | | vector method, Problems | | |
| | | involving vector | | |
| | | application. | | |
| | ⊿ th | Fauilibrium: Static and dynamic | | |
| | т | equilibrium static in determinacy | | |
| | | equinorium, state in determinacy | | |
| | | | | |
| 3 rd | 5 th | General equations of | | |
| | | equilibrium, Varingnon's theorem. | | |
| | | | | |



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| | 6 th | Lami's theorem, equilibrium of bodies under a force system, Problems. | |
|-----------------|------------------|--|--|
| 4 th | 7 th | Truss and Frames:Truss, classification of truss. | |
| | 8 th | Assumptions in truss analysis, perfect truss. | |
| 5 th | 9 th | Analysis of perfect plane truss using method of joints and method of sections. | |
| | 10 th | Centroid, Centre of mass and Centre of gravity, Determination of centroid. | |
| 6 th | 11 th | Centre of mass and centre of gravity. | |
| | 12 th | Integration method of regular and composite figures and solid objects, Problems. | |
| 7 th | 13 th | Moment of Inertia: Area moment of inertia, mass moment of inertia. | |
| | 14 th | Parallel axis and perpendicular axis theorems. | |
| 8 th | 15 th | Radius of gyration, polar moment of inertia, product of inertia, principle axis. | |



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| | 16 th | Problem based on composite figures and solid objects. | |
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| 9 th | 17 th | Kinematics: Concept of rigid body, velocity and acceleration. | |
| | 18 th | Relative velocity, translation and rotation of rigid bodies. | |
| 10 th | 19 th | Equations of motion for translation and rotation, problems. | |
| | 20 th | Particle Dynamics: Energy methods and momentum methods. | |
| 11 th | 21 th | Newton's laws, work energy equation for a system of particles. | |
| | 22 nd | Linear and angular momentum equations, projectile motion, problem. | |
| 12 th | 23 nd | Shear Force and Bending Moment Diagram for statically determinant beams. | |
| | 24 nd | Classification of beams, types of loads. | |
| 13 th | 25 nd | Shear force and bending moment calculation and their graphical presentation. | |
| | 26 nd | Point of inflection, problem. | |
| 14^{th} | 27 nd | Revision. | |
| | 28^{nd} | Revision. | |
| 15 th | 29 nd | Revision. | |
| | 30 nd | Revision. | |